

**STRUCTURE** Silicon monolithic integrated circuits

**PRODUCT SERIES** Bipolar stepping motor driver

**TYPE** **BD6384EFV**

**FUNCTION**

- PWM constant current controllable two H bridge driver
- Mixed Decay control

○ Absolute maximum ratings ( $T_a=25^{\circ}\text{C}$ )

| Item                          | Symbol  | Limit             | Unit |
|-------------------------------|---------|-------------------|------|
| Supply voltage                | VCC     | 7                 | V    |
|                               | VM0,1,2 | 36                | V    |
| Power dissipation             | Pd      | 1.6 <sup>*1</sup> | W    |
| Input voltage for control pin | VIN     | 0~VCC             | V    |
| RNF voltage                   | VRNF    | 0.5               | V    |
| Maximum output current        | IOUT    | 1.5 <sup>*2</sup> | A    |
| Operating temperature range   | Topr    | -25~+85           | °C   |
| Storage temperature range     | Tstg    | -55~+150          | °C   |
| Junction temperature          | Tjmax   | 150               | °C   |

<sup>\*1</sup> 70mm × 70mm × 1.6mm glass epoxy board. Derating is done at 12.8mW/°C for operating above  $T_a=25^{\circ}\text{C}$ .

<sup>\*2</sup> Do not, however exceed Pd, ASO and Tjmax=150°C.

○ Recommended operating conditions ( $T_a=-25\sim+85^{\circ}\text{C}$ )

| Item           | Symbol  | Min | Typ  | Max                | Unit |
|----------------|---------|-----|------|--------------------|------|
| Supply voltage | VCC     | 3.0 | 5.0  | 5.5                | V    |
|                | VM0,1,2 | 16  | 24   | 28                 | V    |
| Output current | IOUT    | -   | 1000 | 1200 <sup>*3</sup> | mA   |

<sup>\*3</sup> Do not, however exceed Pd, ASO.

This product described in this specification isn't judged whether it applies to COCOM regulations.

Please confirm in case of export.

This product isn't designed for protection against radioactive rays.

Status of this document

The Japanese version of this document is the formal specification.

A customer may use this translation version only for a reference to help reading the formal version.

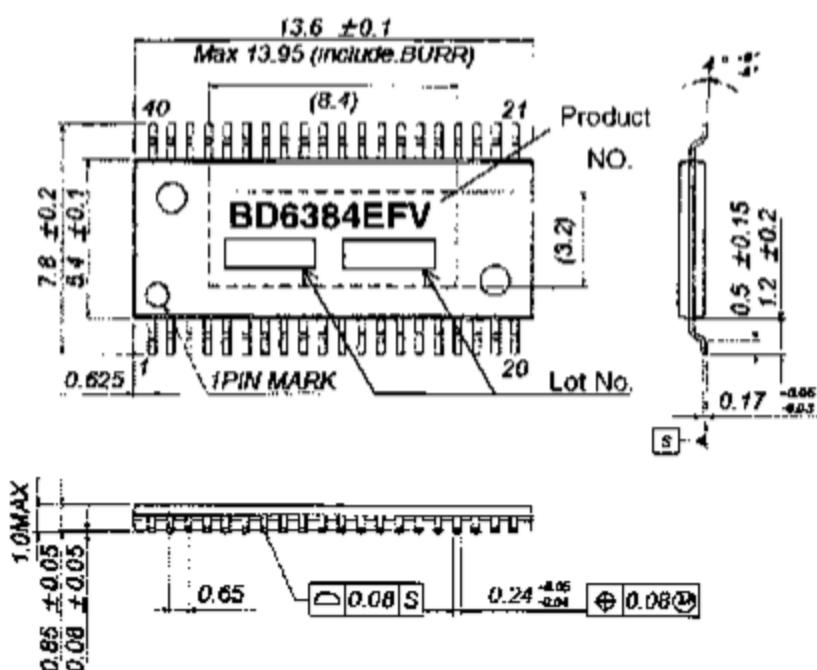
If there are any differences in translation version of this document, formal version takes priority.

○Electrical characteristics (Unless otherwise specified Ta=25°C, VCC=5V, VM=24V)

| Item                           | Symbol   | Limit |       |       | Unit | Conditions                           |
|--------------------------------|----------|-------|-------|-------|------|--------------------------------------|
|                                |          | Min   | Typ   | Max   |      |                                      |
| <b>Whole circuit</b>           |          |       |       |       |      |                                      |
| VCC circuit current at standby | ICCST    | -     | 0     | 10    | μA   | PS=L                                 |
| VCC circuit current            | ICC      | -     | 3     | 5     | mA   | PS=H, VREFX=2V                       |
| VM current at standby          | IVMST    | -     | 0     | 10    | μA   | PS=L                                 |
| VM circuit current             | IVM      | -     | 1.5   | 3     | mA   | PS=H, VREFX=2V                       |
| <b>Control input VCC=3.3V</b>  |          |       |       |       |      |                                      |
| H level input voltage          | VINH1    | 2.0   | -     | 3.3   | V    |                                      |
| L level input voltage          | VINL1    | 0     | -     | 0.8   | V    |                                      |
| <b>Control input VCC=5.0V</b>  |          |       |       |       |      |                                      |
| H level input voltage          | VINH2    | 2.5   | -     | 5.0   | V    |                                      |
| L level input voltage          | VINL2    | 0     | -     | 0.8   | V    |                                      |
| <b>Output</b>                  |          |       |       |       |      |                                      |
| Output ON resistance           | RON      | -     | 1.2   | 1.44  | Ω    | IOUT=1.0A,<br>Sum of upper and lower |
| Output leak current            | ILEAK    | -     | -     | 10    | μA   |                                      |
| <b>Current control part</b>    |          |       |       |       |      |                                      |
| RNFX_REF input current         | IRNF_REF | -2    | -0.6  | -     | μA   | RNFX_REF=0V                          |
| RNFX input current             | IRNF     | -40   | -20   | -     | μA   |                                      |
| VREFX input current            | IVREF    | -1    | -0.1  | -     | μA   | VREFX=0V                             |
| VREFX input voltage range      | VREF     | 0     | -     | 2     | V    |                                      |
| MTHX input current             | IMTH     | -1    | -0.1  | -     | μA   | MTHX=0V                              |
| MTHX input voltage range       | MTH      | 0     | -     | 2     | V    |                                      |
| Comparator threshold (100%)    | CTHLL    | 0.34  | 0.4   | 0.46  | V    | VREFX=2V,I0x=L,I1x=L                 |
| Comparator threshold (67%)     | CTHHL    | 0.227 | 0.267 | 0.307 | V    | VREFX=2V,I0x=H,I1x=L                 |
| Comparator threshold (33%)     | CTHLH    | 0.113 | 0.133 | 0.153 | V    | VREFX=2V,I0x=L,I1x=H                 |
| Minimum on time                | TMINON   | 0.3   | 0.7   | 1.2   | μsec | R=39kΩ,C=1000pF                      |

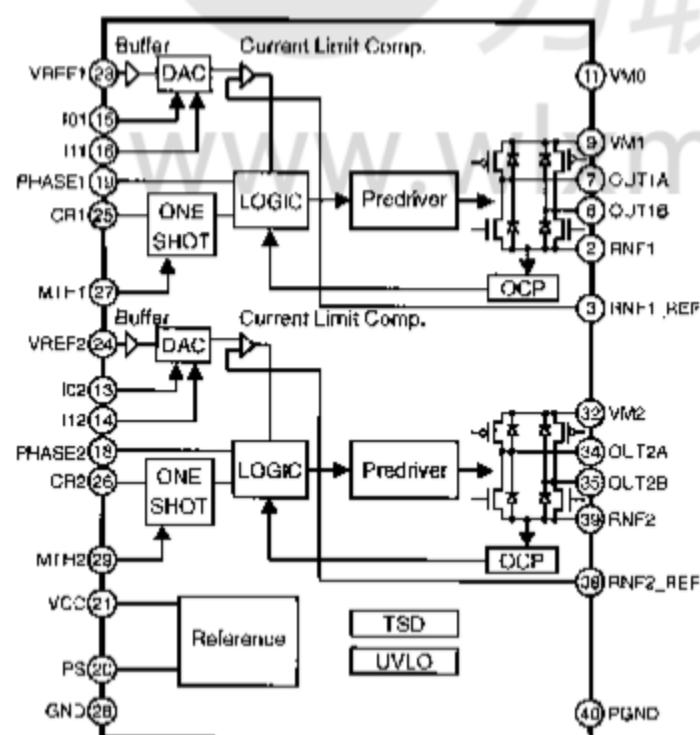
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## ○ Package outline



HTSSOP-B40 (Unit:mm)

## ○ Block diagram



## ○ Pin No. / Pin name

| Pin No. | Pin name | Pin No. | Pin name |
|---------|----------|---------|----------|
| 1       | N.C.     | 21      | VCC      |
| 2       | RNF1     | 22      | N.C.     |
| 3       | RNF1_REF | 23      | VREF1    |
| 4       | N.C.     | 24      | VREF2    |
| 5       | N.C.     | 25      | CR1      |
| 6       | OUT1B    | 26      | CR2      |
| 7       | OUT1A    | 27      | MTH1     |
| 8       | N.C.     | 28      | GND      |
| 9       | VM1      | 29      | MTH2     |
| 10      | N.C.     | 30      | N.C.     |
| 11      | VM0      | 31      | N.C.     |
| 12      | N.C.     | 32      | VM2      |
| 13      | I02      | 33      | N.C.     |
| 14      | I12      | 34      | OUT2A    |
| 15      | I01      | 35      | OUT2B    |
| 16      | I11      | 36      | N.C.     |
| 17      | N.C.     | 37      | N.C.     |
| 18      | PHASE2   | 38      | RNF2_REF |
| 19      | PHASE1   | 39      | RNF2     |
| 20      | PS       | 40      | PGND     |

## Operation Notes

### (1) Absolute maximum ratings

Use of the IC in excess of absolute maximum ratings such as the applied voltage or operating temperature range may result in IC damage. Assumptions should not be made regarding the state of the IC (short mode or open mode) when such damage is suffered. A physical safety measure such as a fuse should be implemented when use of the IC in a special mode where the absolute maximum ratings may be exceeded is anticipated.

### (2) Power supply lines

As return of current regenerated by back EMF of motor happens, take steps such as putting capacitor between power supply and GND as a electric pathway for the regenerated current. Be sure that there is no problem with each property such as emptied capacity at lower temperature regarding electrolytic capacitor to decide capacity value. If the connected power supply does not have sufficient current absorption capacity, regenerative current will cause the voltage on the power supply line to rise, which combined with the product and its peripheral circuitry may exceed the absolute maximum ratings. It is recommended to implement a physical safety measure such as the insertion of a voltage clamp diode between the power supply and GND pins.

### (3) GND potential

Ensure a minimum GND pin potential in all operating conditions.

### (4) Setting of heat

Use a thermal design that allows for a sufficient margin in light of the power dissipation ( $P_d$ ) in actual operating conditions. This IC exposes its frame of the backside of package. Note that this part is assumed to use after providing heat dissipation treatment to improve heat dissipation efficiency . Try to occupy as wide as possible with heat dissipation pattern not only on the board surface but also the backside.

### (5) Actions in strong magnetic field

Use caution when using the IC in the presence of a strong magnetic field as doing so may cause the IC to malfunction.

### (6) ASO

When using the IC, set the output transistor so that it does not exceed absolute maximum ratings or ASO.

### (7) Thermal shutdown circuit

This IC incorporates a TSD (Thermal shutdown) circuit. If the chip becomes the following temperature, coil output to the motor will be open. The TSD circuit is designed only to shut the IC off to prevent runaway thermal operation. It is not designed to protect or guarantee peripheral equipment. Do not use the TSD function to protect peripheral equipment.

| TSD on temperature [°C] (min.) | Hysteresis temperature [°C] (typ.) |
|--------------------------------|------------------------------------|
| 150                            | 25                                 |

### (8) Ground Wiring Pattern

When using both small signal and large current GND patterns, it is recommended to isolate the two ground patterns, placing a single ground point at the application's reference point so that the pattern wiring resistance and voltage variations caused by large currents do not cause variations in the small signal ground voltage. Be careful not to change the GND wiring pattern of any external components, either.

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